

# Permanence for a N-species competitive system with feedback controls

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**Abstract:** By applying the theory of inequality on time scales, we obtain some sufficient conditions which guarantee the permanence of the following N-species competitive system with feedback controls

$$\begin{cases} \dot{x}_i^\Delta(t) = b_i(t) - \sum_{j=1}^N a_{ij}(t) \exp\{x_j(t)\} - \sum_{j=1, j \neq i}^N c_{ij}(t) \exp\{x_i(t) + x_j(t)\} - d_i(t)u_i(t), \\ u_i^\Delta(t) = r_i(t) - e_i(t)u_i(t) + f_i(t) \exp\{x_i(t)\}, i = 1, 2, \dots, N, \end{cases}$$

where  $b_i(t)$ ,  $d_i(t)$ ,  $r_i(t)$ ,  $e_i(t)$ ,  $f_i(t)$ ,  $a_{ij}(t)$  and  $c_{ij}(t)$  are all bounded non-negative almost periodic functions on  $\mathbb{T}$ .

## 1. Introduction

Recently, the dynamic behaviors of Lotka-Volterra predator-prey system have been widely investigated. And it is important to know the existence of periodic solutions of competitive systems. In [1], Ahmad S. has proved that under some certain conditions  $x_1(t)$  is permanence and  $x_2(t)$  is extinction in the following two-species system

$$\begin{cases} \dot{x}_1(t) = x_1(t)[r_1(t) - a_1(t)x_1(t) - b_1(t)x_2(t)], \\ \dot{x}_2(t) = x_2(t)[r_2(t) - a_2(t)x_1(t) - b_2(t)x_2(t)]. \end{cases} \quad (1.1)$$

In order to search for certain schemes (such as harvesting procedure) to ensure system (1.1) coexists under the conditions obtained in [1]. Xiao et al. [2] consider the following feedback controlled system

$$\begin{cases} \dot{x}_1(t) = x_1(t)[r_1(t) - a_1(t)x_1(t) - b_1(t)x_2(t) - d_1(t)u_1(t)], \\ \dot{x}_2(t) = x_1(t)[r_2(t) - a_2(t)x_1(t) - b_2(t)x_2(t) + d_2(t)u_2(t)], \\ \dot{u}_1(t) = -e_1(t)u_1(t) + f_1(t)x_1(t), \\ \dot{u}_2(t) = h_2(t) - e_2(t)u_2(t) - f_2(t)x_2(t). \end{cases} \quad (1.2)$$

Due to the various seasonal effects of the environmental factors in real life situation (e.g. seasonal effects of weather, food supplies, mating habits, harvesting, etc.), it is rational and practical to study the ecosystem with periodic coefficients[3-7].

Up to now, few work has been done for multispecies competitive system on time scales which can unify continuous and discrete situations. In [8], the authors propose the concept of almost periodic time scales and the definition of almost periodic functions on almost periodic time scales. Based on these, our main aim in this paper is to study the permanence of the following system with feedback controls on time scales

$$\begin{cases} \dot{x}_i^\Delta(t) = b_i(t) - \sum_{j=1}^N a_{ij}(t) \exp\{x_j(t)\} - \sum_{j=1, j \neq i}^N c_{ij}(t) \exp\{x_i(t) + x_j(t)\} - d_i(t)u_i(t), \\ u_i^\Delta(t) = r_i(t) - e_i(t)u_i(t) + f_i(t) \exp\{x_i(t)\}, i = 1, 2, \dots, N. \end{cases} \quad (1.3)$$

where  $t \in \mathbb{T}$ ,  $\mathbb{T}$  is an almost periodic time scale,  $x_i(t), i = 1, 2, \dots, N$  is the density of species  $X_i$ ;

$u_i(t), i=1,2,\dots,N$  is feedback control;  $b_i, a_{ij}(t)$  and  $c_{ij}(t)$  denote the intrinsic growth rate, death rate and inter-specific competition, respectively.  $b_i(t), d_i(t), r_i(t), e_i(t), f_i(t), a_{ij}(t)$  and  $c_{ij}(t)$  are all bounded non-negative almost periodic functions on  $\mathbb{T}$ .

For an almost periodic function  $f: \mathbb{T} \rightarrow \mathbb{R}$ , we denote  $f^M = \sup_{t \in \mathbb{T}} f(t)$ ,  $f^m = \inf_{t \in \mathbb{T}} f(t)$ , and we denote the solutions of system (1.3) by  $X(t) = (x_1(t), \dots, x_N(t), u_1(t), \dots, u_N(t))^T$ .

Throughout this paper, we assume that

(H<sub>1</sub>)  $b_i(t), d_i(t), r_i(t), e_i(t), f_i(t), a_{ij}(t)$  and  $c_{ij}(t)$  are all bounded non-negative almost periodic functions on  $\mathbb{T}$  such that

$$\begin{aligned} 0 < b_i^m \leq b_i(t) \leq b_i^M, 0 < d_i^m \leq d_i(t) \leq d_i^M, \\ 0 < r_i^m \leq r_i(t) \leq r_i^M, 0 < e_i^m \leq e_i(t) \leq e_i^M, \\ 0 < f_i^m \leq f_i(t) \leq f_i^M, 0 < a_{ij}^m \leq a_{ij}(t) \leq a_{ij}^M, \\ 0 < c_{ij}^m \leq c_{ij}(t) \leq c_{ij}^M, i, j = 1, 2, \dots, N; \end{aligned}$$

$$(H_2) -b_i^M, -b_i^m, -d_i^M, -d_i^m, -r_i^M, -r_i^m, -e_i^M, -e_i^m, -f_i^M, -f_i^m, -a_{ij}^M, -a_{ij}^m, -c_{ij}^M, -c_{ij}^m \in \mathcal{R}^+;$$

$$(H_3) b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^*\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^*\} - d_i^M(t) u_i^* > 0.$$

## 2. Preliminaries

Let  $\mathbb{T}$  be a nonempty closed subset (time scale) of  $\mathbb{R}$ . The forward and backward jump operators  $\sigma, \rho: \mathbb{T} \rightarrow \mathbb{T}$  and the graininess  $\mu: \mathbb{T} \rightarrow \mathbb{R}$  are defined, respectively, by

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}, \quad \rho(t) = \sup\{s \in \mathbb{T} : s < t\}, \quad \mu(t) = \sigma(t) - t.$$

A point  $t \in \mathbb{T}$  is called left-dense if  $t > \inf \mathbb{T}$  and  $\rho(t) = t$ , left-scattered if  $\rho(t) < t$ , right-dense if  $t < \sup \mathbb{T}$  and  $\sigma(t) = t$ , and right-scattered if  $\sigma(t) > t$ . If  $\mathbb{T}$  has a left-scattered maximum  $m$ , then  $\mathbb{T}^k = \mathbb{T} \setminus \{m\}$ ; otherwise  $\mathbb{T}^k = \mathbb{T}$ . If  $\mathbb{T}$  has a right-scattered minimum  $m$ , then  $\mathbb{T}_k = \mathbb{T} \setminus \{m\}$ ; otherwise  $\mathbb{T}_k = \mathbb{T}$ .

A function  $f: \mathbb{T} \rightarrow \mathbb{R}$  is right-dense continuous provided it is continuous at right-dense point in  $\mathbb{T}$  and its left-side limits exist at left-dense points in  $\mathbb{T}$ . If  $f$  is continuous at each right-dense point and each left-dense point, then  $f$  is said to be a continuous function on  $\mathbb{T}$ .

**Definition 2.1[8]** Assume that  $f: \mathbb{T} \rightarrow \mathbb{R}$  is a function and let  $t \in \mathbb{T}$ . Then we define  $f^\Delta(t)$  to be the number (provided it exists) with the property that given any  $\varepsilon > 0$ , there is a neighborhood  $U$  of  $t$  (i.e.,  $U = (t - \delta, t + \delta) \cap \mathbb{T}$  for some  $\delta > 0$ ) such that

$$|[f(\sigma(t)) - f(s)] - f^\Delta(t)[\sigma(t) - s]| \leq \varepsilon |\sigma(t) - s| \quad \text{for all } s \in U.$$

we call  $f^\Delta(t)$  the delta derivative of  $f$  at  $t$ . The function  $f$  is delta differentiable on  $\mathbb{T}$  provided  $f^\Delta(t)$  exists for all  $t \in \mathbb{T}$ . The set of functions  $f: \mathbb{T} \rightarrow \mathbb{R}$  that are delta differentiable and whose delta derivative are rd-continuous functions is denoted by  $C_{rd}^1 = C_{rd}^1(\mathbb{T}) = C_{rd}^1(\mathbb{T}, \mathbb{R})$ .

**Definition 2.2[8]** A function  $p: \mathbb{T} \rightarrow \mathbb{R}$  is called regressive provided  $1 + \mu(t)p(t) \neq 0$  for all  $t \in \mathbb{T}^k$ . The set of all regressive and rd-continuous functions  $p: \mathbb{T} \rightarrow \mathbb{R}$  will be denoted by  $\mathcal{R} = \mathcal{R}(\mathbb{T}) = \mathcal{R}(\mathbb{T}, \mathbb{R})$ . We define the set  $\mathcal{R}^+ = \mathcal{R}^+(\mathbb{T}, \mathbb{R}) = \{p \in \mathcal{R} : 1 + \mu(t)p(t) > 0, \forall t \in \mathbb{T}\}$ .

**Definition 2.3[8]** A time scale  $\mathbb{T}$  is called an almost periodic time scale if  $\Pi := \{\tau \in \mathbb{R} : t + \tau \in \mathbb{T}, \forall t \in \mathbb{T}\} \neq \{0\}$ .

Throughout this paper, we restrict our discussion on almost periodic time scales.

**Definition 2.4[8]** Let  $\mathbb{T}$  be an almost periodic time scale. A function  $f: \mathbb{T} \rightarrow \mathbb{R}$  is said to be almost periodic on  $\mathbb{T}$ , if for any  $\varepsilon > 0$ , the set  $E(\varepsilon, f) = \{\tau \in \Pi : |f(t + \tau) - f(t)| < \varepsilon, \forall t \in \mathbb{T}\}$  is relatively dense in  $\mathbb{T}$ , that is, for any  $\varepsilon > 0$ , there exists a constant  $l(\varepsilon) > 0$  such that each interval of

length  $l(\varepsilon)$  contains at least one  $\tau \in E(\varepsilon, f)$  such that  $|f(t+\tau) - f(t)| < \varepsilon, \forall t \in \mathbb{T}$ . The set  $E(\varepsilon, f)$  is called the  $\varepsilon$ -translation set of  $f(t)$ ,  $\tau$  is called the  $\varepsilon$ -translation number of  $f(t)$ , and  $l(\varepsilon)$  is called the inclusion of  $E(\varepsilon, f)$ .

**Lemma 2.1[8]** Let  $-a \in \mathcal{R}^+$ .

- (i) If  $x^\Delta(t) \leq b - ax(t)$ , then for  $t > t_0$ ,  $x(t) \leq x(t_0)e_{(-a)}(t, t_0) + \frac{b}{a}(1 - e_{(-a)}(t, t_0))$ . In particular, if  $a > 0$ , we have  $\limsup_{t \rightarrow +\infty} x(t) \leq \frac{b}{a}$ .
- (ii) If  $x^\Delta(t) \geq b - ax(t)$ , then for  $t > t_0$ ,  $x(t) \geq x(t_0)e_{(-a)}(t, t_0) + \frac{b}{a}(1 - e_{(-a)}(t, t_0))$ . In particular, if  $a > 0$ , we have  $\liminf_{t \rightarrow +\infty} x(t) \geq \frac{b}{a}$ .

### 3. Permanence

In this section, we establish some permanence results for system (1.3). Firstly, we provide the definition of permanence.

**Definition 3.1** System (1.3) is said to be permanent if there exist positive constants  $x_{i_*}, x_i^*, u_{i_*}, u_i^*$  which are independent of the solutions of the system, such that any positive solution  $X(t)$  of system (1.3) satisfies

$$x_{i_*} \leq \liminf_{t \rightarrow +\infty} x_i(t) \leq \limsup_{t \rightarrow +\infty} x_i(t) \leq x_i^*, \quad u_{i_*} \leq \liminf_{t \rightarrow +\infty} u_i(t) \leq \limsup_{t \rightarrow +\infty} u_i(t) \leq u_i^*, \quad i = 1, 2, \dots, N.$$

**Theorem 3.1** Assume that  $(H_1)$ ,  $(H_2)$  hold. Then every solution  $X(t)$  of system (1.3) satisfies

$$\limsup_{t \rightarrow +\infty} x_i(t) \leq x_i^*, \quad \limsup_{t \rightarrow +\infty} u_i(t) \leq u_i^*, \quad i = 1, 2, \dots, N,$$

where

$$x_i^* = \frac{b_i^M - a_{ii}^m}{a_{ii}^m}, \quad u_i^* = \frac{r_i^M + f_i^M \exp\{x_i^*\}}{e_i^m}, \quad i = 1, 2, \dots, N.$$

*Proof* From the first equation of (1.3), we have

$$\begin{aligned} x_i^\Delta(t) &\leq b_i(t) - \sum_{j=1}^N a_{ij}(t) \exp\{x_j(t)\} \\ &\leq b_i(t) - a_{ii}(t) \exp\{x_i(t)\} \\ &\leq b_i(t) - a_{ii}(t)(x_i(t) + 1)n \\ &\leq b_i^M - a_{ii}^m - a_{ii}^m x_i(t). \end{aligned}$$

It follows from Lemma 2.1 (i), that

$$\limsup_{t \rightarrow +\infty} x_i(t) \leq x_i^*.$$

Then for any  $\varepsilon > 0$ , there exists a  $t_0 \in \mathbb{T}$  such that  $x_i(t) \leq x_i^* + \varepsilon$  for all  $t \geq t_0$ . While, from the second equation of (1.3), we get

$$\begin{aligned} u_i^\Delta(t) &\leq r_i(t) - e_i(t)u_i(t) + f_i(t) \exp\{x_i^* + \varepsilon\} \\ &\leq r_i^M + f_i^M \exp\{x_i^* + \varepsilon\} - e_i^m u_i(t). \end{aligned}$$

Letting  $\varepsilon \rightarrow 0$ , we get

$$\limsup_{t \rightarrow +\infty} u_i(t) \leq u_i^*.$$

**Theorem 3.2** Assume that  $(H_1)$  -  $(H_3)$  hold, then every solution  $X(t)$  of system (1.1) satisfies

$$\liminf_{t \rightarrow +\infty} x_i(t) \geq x_{i_*}, \quad \liminf_{t \rightarrow +\infty} u_i(t) \geq u_{i_*},$$

where

$$x_{i_*} = \ln \frac{b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^*\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^*\} - d_i^M u_i^*}{a_{ii}^M},$$

$$u_{i_*} = \frac{r_i^m + e_i^m x_{i_*}}{e_i^M}.$$

*Proof* According to Theorem 3.1, for any  $\varepsilon > 0$ , there exists a  $t_0 \in \mathbb{T}$ , for any  $t > t_0$  and  $t \in \mathbb{T}$  such that,  $u_i(t) \leq x_i^* + \varepsilon, x_i(t) \leq u_i^* + \varepsilon$ . Then for  $t \geq t_0$ , from the first equation of (1.3), we have

$$\begin{aligned} x_i^\Delta(t) &= b_i(t) - \sum_{j=1, j \neq i}^N a_{ij} \exp\{x_j(t)\} - \sum_{j=1, j \neq i}^N c_{ij} \exp\{x_i(t) + x_j(t)\} \\ &\quad - d_i(t)u_i(t) - a_{ii}(t)\exp\{x_i(t)\} \\ &\geq b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} \\ &\quad - d_i^M(t)u_i^* - a_{ii}^M \exp\{x_i(t)\}. \end{aligned} \quad (3.1)$$

Now, we claim for any  $\varepsilon > 0$ , there exists a  $t_0 \in \mathbb{T}$ , for any  $t > t_0$  and  $t \in \mathbb{T}$  such that,

$$\begin{aligned} N(t) &= b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} - d_i^M(t)u_i^* - a_{ii}^M \exp\{x_i(t)\} \\ &\leq 0, \end{aligned} \quad (3.2)$$

where

$$x_i(t) \geq \ln \frac{b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} - d_i^M(t)u_i^*}{a_{ii}^M}. \quad (3.3)$$

Otherwise, there exists a  $t_1 > t_0$  and  $t_1 \in \mathbb{T}$ , when  $t \geq t_1$ , such that,

$$\begin{aligned} N_0(t) &= b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} - d_i^M(t)u_i^* - a_{ii}^M \exp\{x_i(t)\} \\ &> 0, \end{aligned} \quad (3.4)$$

where

$$x_i(t_1) < \ln \frac{b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} - d_i^M(t)u_i^*}{a_{ii}^M}, \quad (3.5)$$

and for  $t \in [t_0, t_1)_{\mathbb{T}}$ ,  $N(t) \leq 0$ .

From (3.3) and (3.5), we get

$$x_i^\Delta(t_1) \leq 0. \quad (3.6)$$

But from (H<sub>3</sub>) and (3.1) we have

$$x_i^\Delta(t_1) > 0,$$

which is a contradiction with (3.6). Thus, we have proved the claim.

Then, from (3.2), we arrive that

$$x_i(t) \geq \ln \frac{b_i^m - \sum_{j=1, j \neq i}^N a_{ij}^M \exp\{x_j^* + \varepsilon\} - \sum_{j=1, j \neq i}^N c_{ij}^M \exp\{x_i^* + x_j^* + 2\varepsilon\} - d_i^M(t)u_i^*}{a_{ii}^M}.$$

Letting  $\varepsilon \rightarrow 0$ , we get  $\liminf_{t \rightarrow +\infty} x_i(t) \geq x_{i_*}$ .

For any  $\varepsilon > 0$ , there exists a  $t_2 \in \mathbb{T}$ , for any  $t > t_2$  and  $t \in \mathbb{T}$  such that,  $x_i(t) \leq x_{i_*} - \varepsilon$ , for  $t \geq t_2$ .

Owing to the second equation of system (1.3) we get,

$$\begin{aligned} u_i^\Delta(t) &= r_i(t) - e_i(t)u_i(t) + f_i(t)x_i(t) \\ &\geq r_i^m + f_i^m(x_{i_*} - \varepsilon) - e_i^M u_i(t). \end{aligned}$$

Letting  $\varepsilon \rightarrow 0$ , we get

$$u_i^\Delta(t) \geq r_i^m + f_i^m x_{i_*} - e_i^M u_i(t),$$

according to Lemma 2.1 (i), it follows that,

$$\liminf_{t \rightarrow +\infty} u_i(t) \geq u_{i_*}.$$

Obviously, we can obtain the following result.

**Theorem 3.3** Assume that  $(H_1) - (H_3)$  hold. Then system (1.3) is permanent.

We denote by  $\Omega$  for all solutions  $X(t)$  of system (1.3) satisfying  $x_{i_*} \leq x_i(t) \leq x_{i^*}$ ,  $u_{i_*} \leq u_i(t) \leq u_{i^*}$ , for  $t \in \mathbb{T}$ ,  $i = 1, 2, \dots, N$ .

**Theorem 3.4** Assume  $(H_1) - (H_3)$  hold, then  $\Omega \neq \emptyset$ .

*Proof* Since  $b_i(t), d_i(t), r_i(t), e_i(t), f_i(t), a_{ij}(t)$  and  $c_{ij}(t)$  all are almost periodic functions on  $\mathbb{T}$ , then there exists a sequence  $\tau = \{\tau_p\} \subseteq \mathbb{T}$  with  $\tau_p \rightarrow +\infty$  for  $p \rightarrow +\infty$  such that

$$\begin{aligned} b_i(t + \tau_p) &\rightarrow b_i(t), d_i(t + \tau_p) \rightarrow d_i(t), r_i(t + \tau_p) \rightarrow r_i(t), \\ e_i(t + \tau_p) &\rightarrow e_i(t), f_i(t + \tau_p) \rightarrow f_i(t), a_{ij}(t + \tau_p) \rightarrow a_{ij}(t), \\ a_{ij}(t + \tau_p) &\rightarrow a_{ij}(t), \text{ for } p \rightarrow +\infty. \end{aligned} \quad (3.7)$$

According to the Theorem 3.1 and Theorem 3.2, for any  $\varepsilon > 0$ , there exists a  $t_+ \in \mathbb{T}$  such that

$$x_{i_*} - \varepsilon \leq x_i(t) \leq x_{i^*} + \varepsilon, \quad u_{i_*} - \varepsilon \leq u_i(t) \leq u_{i^*} + \varepsilon, \text{ for all } t \geq t_+.$$

For  $t > t_+ - \tau_p$ ,  $p = 1, 2, \dots, N$ , we denote  $x_{ip}(t) = x_i(t + \tau_p)$  and  $u_{ip}(t) = u_i(t + \tau_p)$ . For any positive integer  $q$ , it is easy to see that there exist sequences  $\{x_{ip}(t) : p \geq q\}$  and  $\{u_{ip}(t) : p \geq q\}$  such that the sequences  $\{x_{ip}(t)\}$  and  $\{u_{ip}(t)\}$  have subsequences, converging on any finite interval of  $\mathbb{T}$  for  $p \rightarrow +\infty$ , respectively. For the convenience of expression, we denoted by  $\{x_{ip}(t)\}$  and  $\{u_{ip}(t)\}$  again. Thus we have sequences  $\{m_i(t)\}$  and  $\{n_i(t)\}$  such that

$$x_{ip}(t) \rightarrow m_i(t), u_{ip}(t) \rightarrow n_i(t), \text{ for } p \rightarrow +\infty. \quad (3.8)$$

Combining with

$$\begin{cases} x_{ip}^\Delta(t) = b_i(t + \tau_p) - \sum_{j=1}^N a_{ij}(t + \tau_p) \exp\{x_{ip}(t)\} - d_i(t + \tau_p) u_{ip}(t) \\ \quad - \sum_{j=1, j \neq i}^N c_{ij}(t + \tau_p) \exp\{x_{jp}(t) + x_{ip}(t)\}, \\ u_{ip}^\Delta(t) = r_i(t + \tau_p) - e_i(t + \tau_p) u_{ip}(t) + f_i(t + \tau_p) \exp\{x_{ip}(t)\}, \end{cases} \quad (3.9)$$

from (3.7) and (3.8), for  $p \rightarrow +\infty$ , (3.9) arrives to

$$\begin{cases} m_i^\Delta(t) = b_i(t) - \sum_{j=1}^N a_{ij}(t) \exp\{m_i(t)\} - d_i(t) n_i(t) \\ \quad - \sum_{j=1, j \neq i}^N c_{ij}(t) \exp\{m_j(t) + m_i(t)\}, \\ n_i^\Delta(t) = r_i(t) - e_i(t) n_i(t) + f_i(t) \exp\{m_i(t)\}. \end{cases} \quad (3.10)$$

We can easily see that the solution of (3.10)

$$Y(t) = (m_1(t), m_2(t), \dots, m_N(t), n_1(t), n_2(t), \dots, n_N(t))^T,$$

is a solution of system (1.3), moreover for any  $\varepsilon > 0$  and for all  $t \in \mathbb{T}$  meet the following consideration

$$x_{i_*} - \varepsilon \leq m_i(t) \leq x_{i^*} + \varepsilon, \quad u_{i_*} - \varepsilon \leq n_i(t) \leq u_{i^*} + \varepsilon.$$

Since  $\varepsilon$  is an arbitrary small positive number, it follows that  $x_{i_*} \leq m_i(t) \leq x_{i^*}, u_{i_*} \leq n_i(t) \leq u_{i^*}$ , for all  $t \in \mathbb{T}$ .

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